

Espressif 8266 and 32 platforms



A short overview

- Short description of what they are
- History
- Programming-environments
- Indepth on both ESP8266 and ESP32
- Questions, comments, tomatoes

History

- Suddenly available as 'arduino wifi module'
- Investigations reveal powerful platform
- Documentation gets translated, arduino gets ported
- ESP8266 appears everywhere (sonoff, wifi-lamps/ledstrips/etc)
- ESP32 addresses many shortcomings and improves flexibility for users of the platform greatly.

ESP-01

- 8 pin 'module', non FCC compliant
- AT-command-set 'wifi' chip
- Undocumented but obviously 'capable of more than an atmel avr8 chip.
- Soon after the world notices esp-01, more models pop up.

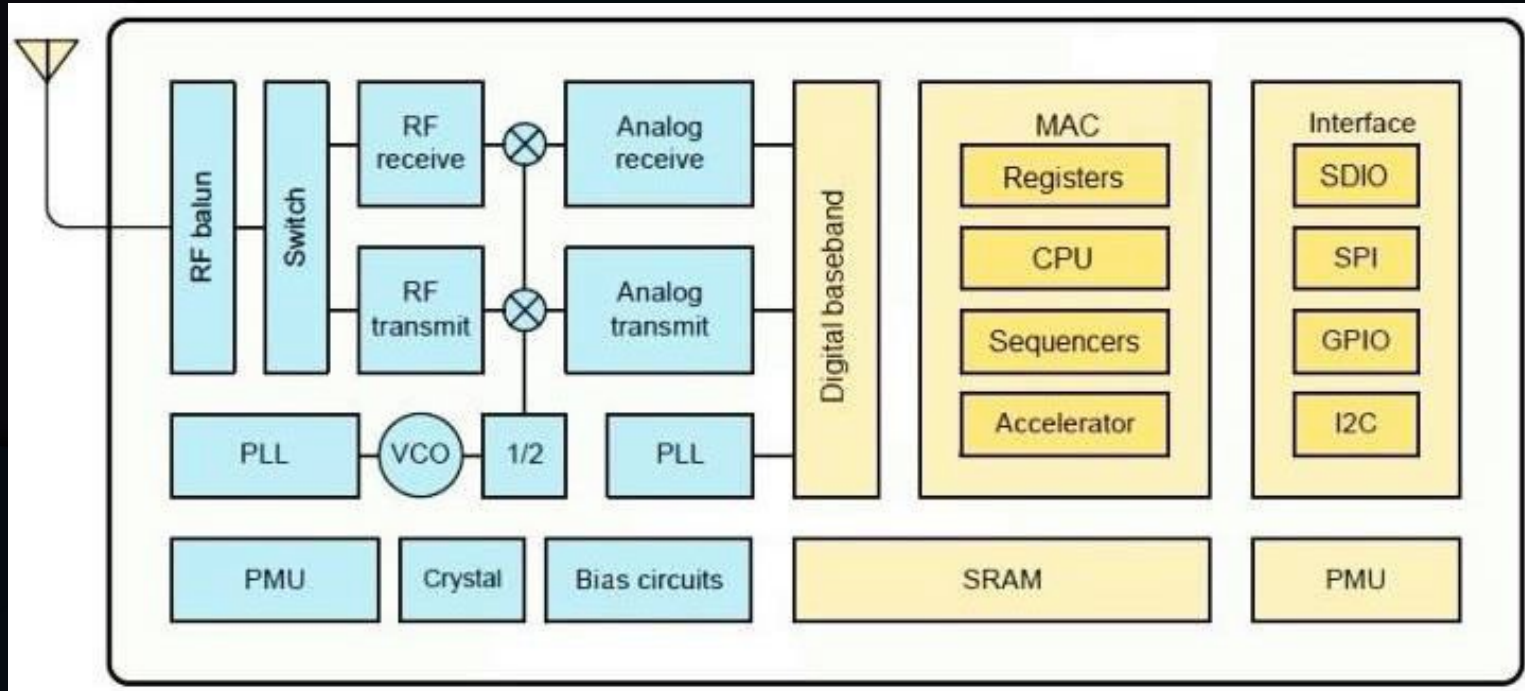
ESP8266



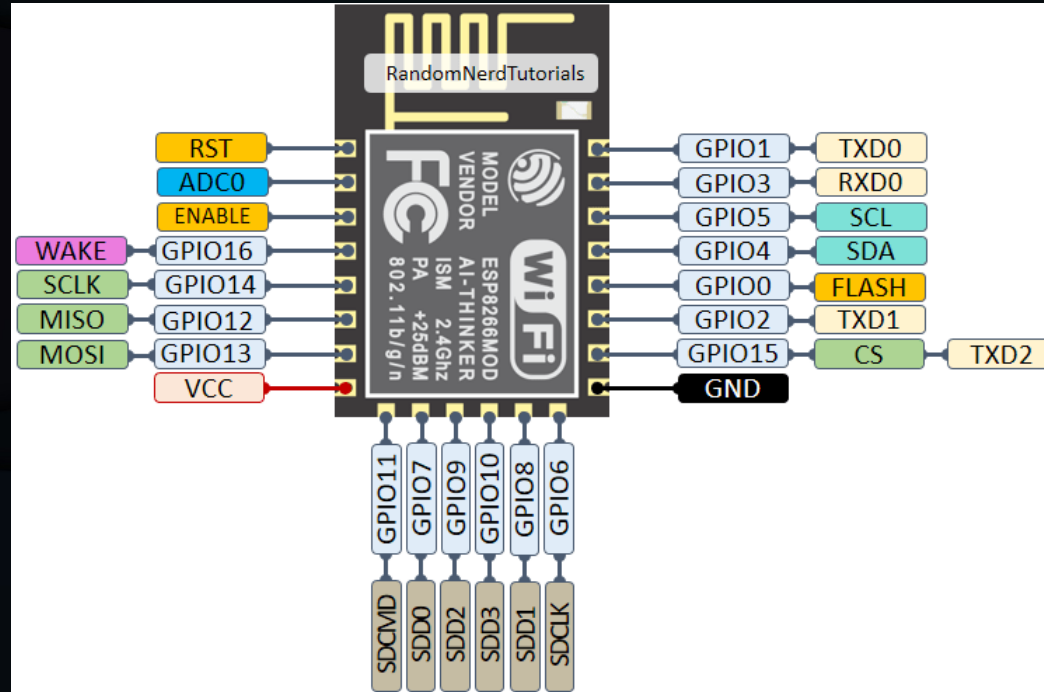
ESP8266

- Single core , up to 160Mhz, 32-bit RISC
- Can use external (flash) mem
- WiFi 802.11n radio integrated
- Sleep-mode abilities
- A host of built-in 'peripherals'
- Available as 'chip', but mostly sold as 'module' (with or without FCC certification)
- ESP-12E/F : 16mm x 24mm

ESP8266 blocks



ESP8266, module

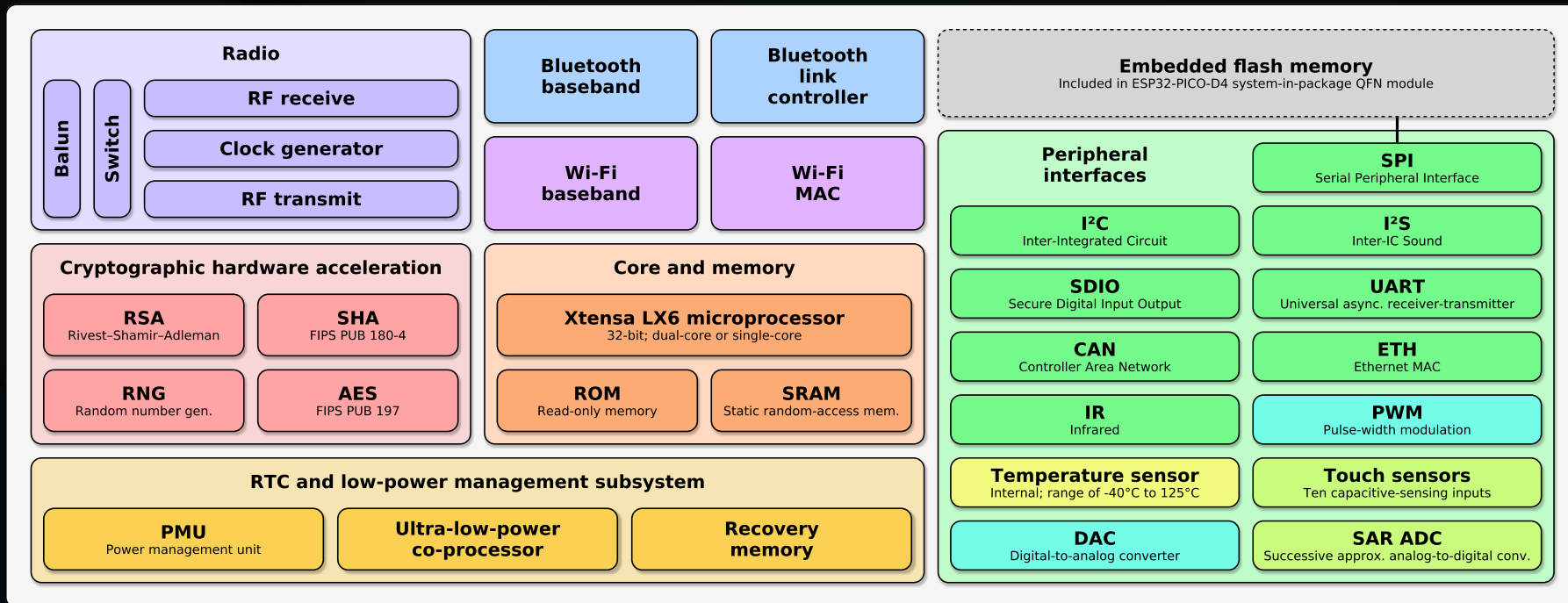


ESP32

- Dual Core, up to 240Mhz, 32-bit risc CPU
- WiFi included, bluetooth added
- 'ulp' core alive while it (deep)sleep
- More peripheral choice
- Less application constraints due to dual-CPU
- Greater pin-flexibility due to GPIO-Matrix/IO-Mux
- 18mm x 25mm (2mm x 1mm larger than ESP8266)

ESP32, blocks

Espressif ESP32 Wi-Fi & Bluetooth Microcontroller — Function Block Diagram



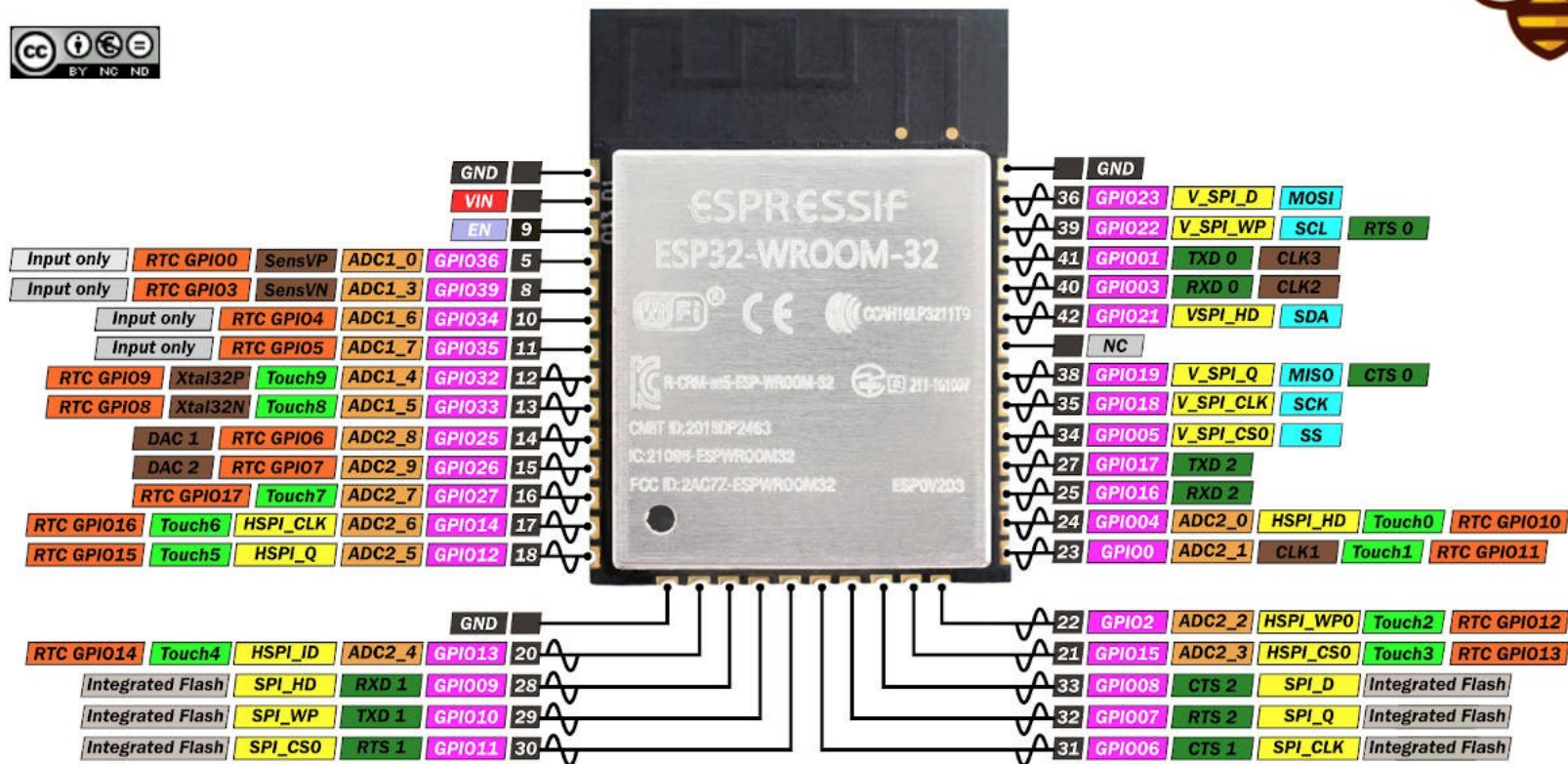
ESP32, module

ESP32-wroom-32



PINOUT

www.mischianti.org

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ESP's side-by-side 1/2

	ESP8266	ESP32
		
MCU	Xtensa Single-core 32-bit L106	Xtensa Dual-Core 32-bit LX6 with 600 DMIPS
802.11 b/g/n Wi-Fi	HT20	HT40
Bluetooth	X	Bluetooth 4.2 and BLE
Typical Frequency	80 MHz	160 MHz
SRAM	X	✓
Flash	X	✓

ESP's side-by-side 2/2

GPIO	17	34
Hardware /Software PWM	None / 8 channels	None / 16 channels
SPI/I2C/I2S/UART	2/1/2/2	4/2/2/2
ADC	10-bit	12-bit
CAN	X	✓
Ethernet MAC Interface	X	✓
Touch Sensor	X	✓
Temperature Sensor	X	✓ (old versions)
Hall effect sensor	X	✓
Working Temperature	-40°C to 125°C	-40°C to 125°C
Price	\$ (3\$ - \$6)	\$\$ (\$6 - \$12)

ESP's, how to use as Arduino

- Requires an 'arduino-core' package
- <https://github.com/esp8266/Arduino>
- <https://github.com/espressif/arduino-esp32>
- Needs proper 'strapping' of boot-pins
- Requires (usb-to)serial connection
- USB=5v, ESP=3.3v; board needs voltage-regulator
- Components/boards need to work with 3.3V logic

ESP8266 Arduino Core install

- Arduino 1.65 (1.66 has issues)
- Preferences → Additional board Manager URL:
- http://arduino.esp8266.com/stable/package_esp8266com_index.json
http://arduino.esp8266.com/stable/package_esp8266com_index.json
- Board-manager → esp8266 → install
- PlatformIO: included/automatic

ESP32 Arduino Core Install

- Latest Arduino IDE
- Preferences → Additional Board Manager URLs:
- https://dl.espressif.com/dl/package_esp32_index.json
- http://arduino.esp8266.com/stable/package_esp8266com_index.json
- Board-manager → ESP32 → Install
- PlatformIO: included/automatic

ESP's not mentioned (GOOD) things

- GPIO-Matrix/IO-MUX, zomg
- Interrupt-sources, zomg
- Former slide has a lie: ESP32 has HW-PWM (16 channels)
- Sleep-modes (!) on ESP32 can go down to $10\mu\text{A}$ consumption with RTC and TOUCH working(!)

ESP's not mentioned (BAD) things

- Some pins are more special then others (bootstrap pins need certain state at boot)
- 3.3Volt power!
- Wifi + other functions can collide esp. on esp8266 (yield())
- Many boards available, no 'default' footprint.

Peripheral zoo, GPIO 17* vs 34*

- 'digital' pin
- Either 'Input' or 'Output' (`pinMode(pin,mode)`)
- `digitalRead/digitalWrite`
- ESP8266 requires careful planning, ESP32 allows flexible remapping
- 18 pins on esp32 are 'rtc_gpio', work in deep sleep
- * Some pins 'useless': require specific state at boot

GPIO code

```
void setup() {  
  // initialize digital pin LED_BUILTIN as an output.  
  pinMode(LED_BUILTIN, OUTPUT);  
}  
  
// the loop function runs over and over again forever  
void loop() {  
  digitalWrite(LED_BUILTIN, HIGH); // turn the LED on (HIGH is the voltage level)  
  delay(1000);                     // wait for a second  
  digitalWrite(LED_BUILTIN, LOW);  // turn the LED off by making the voltage LOW  
  delay(1000);                     // wait for a second  
}
```

Peripheral zoo, PWM, 0vs16

- LEDC pwm for led/sound/power
- MCPWM for motor-control, has 'input' logic
- Software PWM costs CPU-time, can be complex
- ESP32 has groups of 8 channels of PWM, connectable to any* GPIO

LEDC code

```
void setup(){  
    // configure LED PWM functionalitites  
    // channel, basefreq, resolution  
    ledcSetup(0, 5000, 8);  
  
    // attach the channel to the GPIO to be controlled  
    LedcAttachPin(0, 16);  
}  
void loop() {  
    for(int dutyCycle = 0; dutyCycle <= 255; dutyCycle++){  
        // changing the LED brightness with PWM  
        ledcWrite(ledChannel, dutyCycle);  
        delay(15);  
    }  
}
```

Peripheral zoo, ADC 1vs18*

- ESP8266 has 10bit, ESP32 has 12bit
- ESP32 has two 'groups'. Second group blocks with wifi; like with esp8266 ADC
- Some pins not 'useful' due to boot-strap function

ADC code

```
/*****
```

```
Rui Santos
```

```
Complete project details at https://randomnerdtutorials.com
```

```
*****/
```

```
const int analogInPin = A0; // ESP8266 Analog Pin ADC0 = A0
```

```
int sensorValue = 0; // value read from the pot
```

```
void setup() {
```

```
  // initialize serial communication at 115200
```

```
  Serial.begin(115200);
```

```
}
```

```
void loop() {
```

```
  // read the analog in value
```

```
  sensorValue = analogRead(analogInPin);
```

```
  // print the readings in the Serial Monitor
```

```
  Serial.print("sensor = ");
```

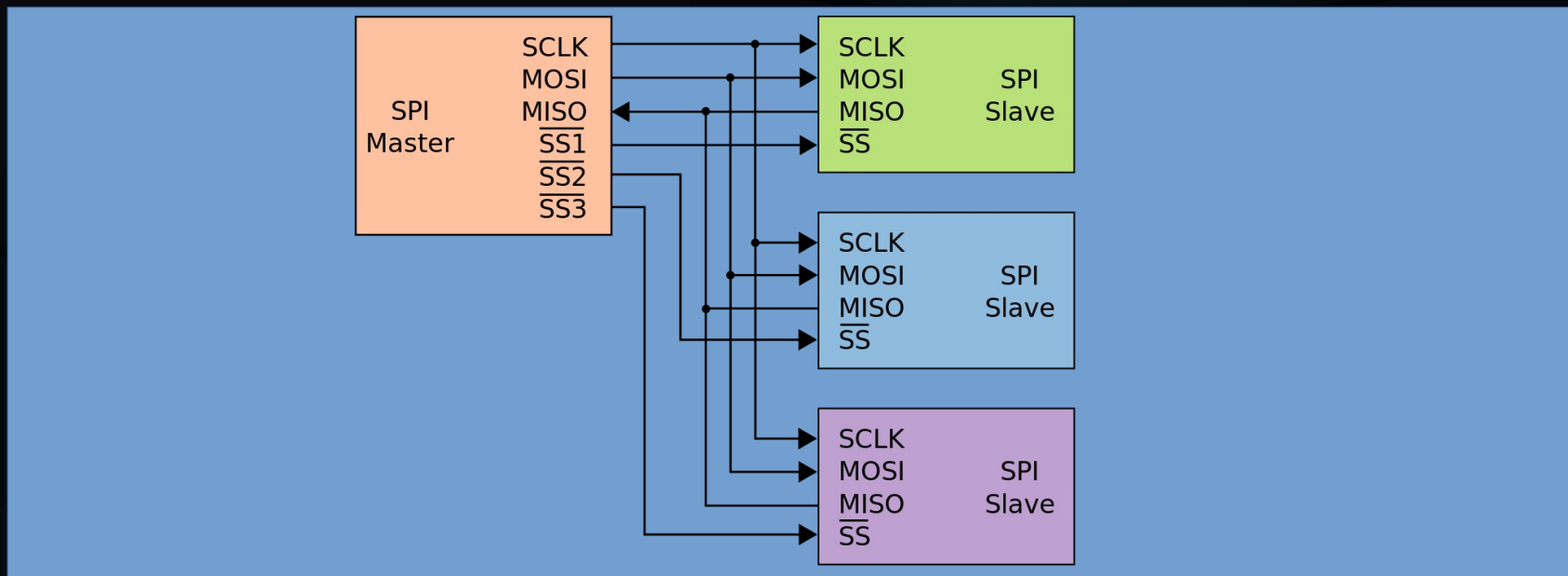
```
  Serial.print(sensorValue);
```

```
  delay(1000);
```

```
}
```


Peripheral zoo, SPI, 2 vs 3 (4?)

- SPI = Serial Peripheral Interface



Peripheral zoo, SPI

- Dot-matrix LCD's
- SD/MMC cards (require pullup-resistors)
- Flash-chips
- LoRa radio-chipsets (RFM95, SX127x)
- High-speed serial IO (shift-registers) IO-expanding, led-driving (direct-mode)

SPI code

```
#include "SPI.h"

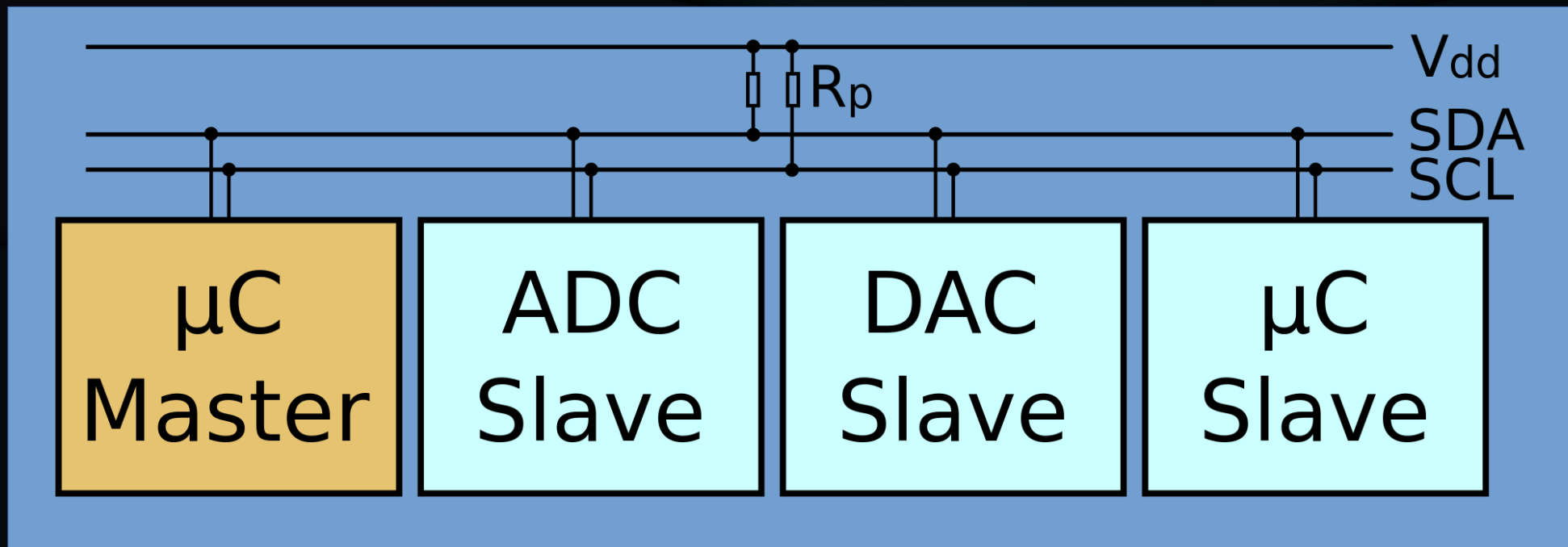
char buff[]="Hello World\n";

void setup() {
  SPI.begin();
}

void loop() {
  for(int i=0; i<sizeof buff; i++)
  {
    SPI.transfer(buff[i]);
  }
  delay(1000);
}
```

Peripheral Zoo, I2C, 1 vs 2

- I2C = Inter-Integrated-Circuit (I-Squared-C)



Peripheral zoo, I2C

- IO-expanders (character-LCD's, relay-boards)
- Eeproms
- Real-time-clock chips
- Temperature-chips
- PWM-chips (led-drivers)

I2C Code

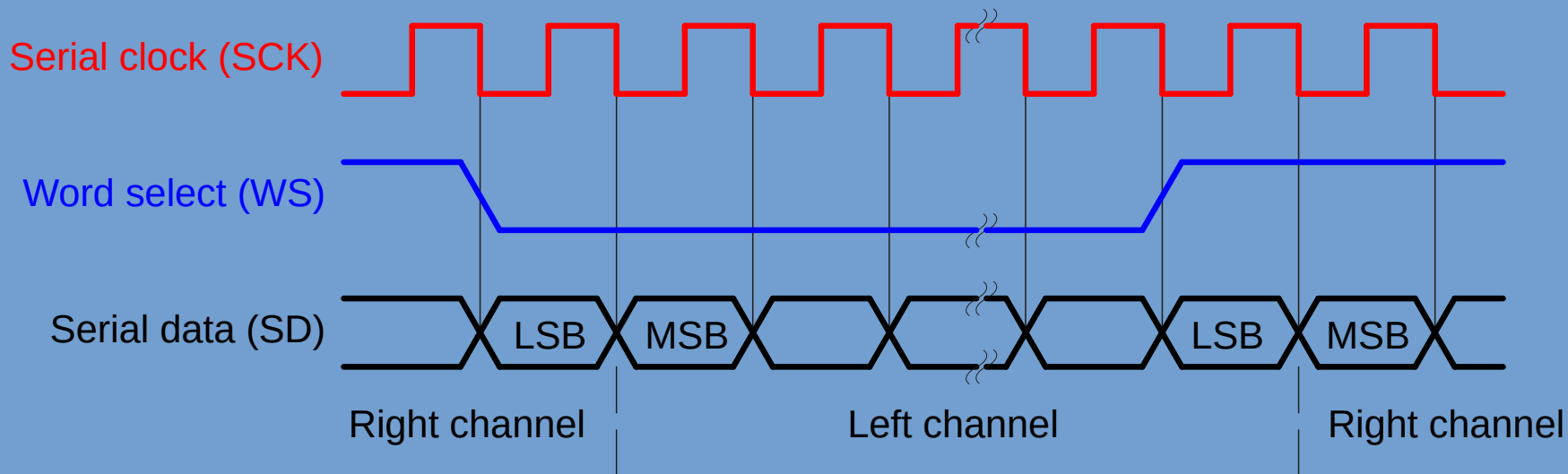
```
#include <Wire.h>

void setup() {
  Wire.begin()
  delay(100)
  Wire.beginTransmission(address)
  Wire.write(register_address)
  Wire.write(data)
  Wire.endTransmission()
}

void loop() {
  // do some transfer to chip to get it to prepare data
  Wire.requestFrom(address, amount)
  if (Wire.available() <= 2) {
    for (i=0, i<amount, i++) {
      bla=Wire.read()
    }
  }
}
```

Peripheral Zoo, I2S, 1+1 vs 2

- I2S , Inter-IC Sound, I-Squared-S



Peripheral Zoo, I2S

- Meant for digital audio (S/PDIF)
- Useful for high-speed serial I/O
- Often used for 'digital' led-strips

Peripheral Zoo, UART, 2 vs 3

- Universal Asynchronous Receiver Transmitter
- Rx/Tx
- CTS/DTS
- IrDA (over infrared)
- RS232/RS485 : different types of signals

Peripheral Zoo, UART

- Used for programming and monitoring
- Useful for communication between modules
- Useful for long-distance communication
- Max232 for 'rs232' levels
- RS485 also available

UART Code

```
void setup() {  
    Serial.begin(9600)  
  
}  
void loop() {  
    Serial.print("This is a stupid example")  
    delay(100)  
}
```

Peripheral zoo, DAC 0 vs 2

- ESP32 , GPIO 25 + 26
- 8-bit.
- Can interoperate with i2s-peripheral

Peripheral Zoo, Touch, 0 vs 10

- Capacitive pads, current-less
- Can trigger interrupt even in sleep-mode
- Can be single-channel 'button'
- Multiple-channels can be combined into 'slider' or 'ring' with careful design

Touchpin Code

```
// ESP32 Touch Test – Randomnerdtutorials.com
```

```
// Just test touch pin - Touch0 is T0 which is on GPIO 4.
```

```
void setup() {
```

```
  Serial.begin(115200);
```

```
  delay(1000); // give me time to bring up serial monitor
```

```
  Serial.println("ESP32 Touch Test");
```

```
}
```

```
void loop() {
```

```
  Serial.println(touchRead(4)); // get value of Touch 0 pin = GPIO 4
```

```
  delay(1000);
```

```
}
```

Peripheral Zoo, PCNT, 0vs8

- ESP32 has 8 pulse-counters of 16bits
- Can connect to any gpio*
- Can count up, down, do interrupts

Peripheral Zoo, RMT, 0 vs 8

- Remote Receiver or Transmitter
- Each channel can either be Rx or Tx
- Takes care of modulation (38khz, 48khz, etc)
- Can be used for other purposes (sound, leds)

Peripheral Zoo, CAN 0 vs 1

- Used in automotive industry
- Requires some external circuitry

Peripheral Zoo, Ethernet 0 vs 1

- 100Mbit 'MAC' controller
- Requires external 'PHY' chip + magnetics
- Communicates via RMII (Reduced Media Independent Interface)
- GPIO 0, 19, 21, 22, 25, 26, 27 are fixed
- 3 more GPIO required, can be chosen by user
- Layout for working ethernet-setup is tricky/picky

Peripheral Zoo, WiFi, 1vs1

- HT20 vs HT40 (wider band, higher speed)
- WiFi, network, TCP/IP CPU intensive
- Modules available with connectors
- Uses same radio + antenn as Bluetooth
- EspNOW mesh-protocol available

ESP Wifi Code

```
#include <ESP8266WiFi.h>    // Include the Wi-Fi library for ESP8266
// #include <WiFi.h> // Include the Wi-Fi library for ESP32

const char* ssid    = "SSID";    // The SSID (name) of the Wi-Fi network you want to connect to
const char* password = "PASSWORD"; // The password of the Wi-Fi network

void setup() {
    Serial.begin(115200);    // Start the Serial communication to send messages to the computer
    delay(10);
    Serial.println("\n");

    WiFi.begin(ssid, password);    // Connect to the network
    Serial.print("Connecting to ");
    Serial.print(ssid); Serial.println(" ...");

    int i = 0;
    while (WiFi.status() != WL_CONNECTED) { // Wait for the Wi-Fi to connect
        delay(1000);
        Serial.print(++i); Serial.print(" ");
    }

    Serial.println("\n");
    Serial.println("Connection established!");
    Serial.print("IP address:");
    Serial.println(WiFi.localIP());    // Send the IP address of the ESP to the computer
}

void loop() { }
```

Peripheral Zoo, Bluetooth, 0 vs 1

- Works but limited examples/docs
- BLE 'sensing' works
- Audio works
- Input-device works
- Meshing protocol available

Peripheral Zoo, SecureElement 0vs1

- Accelerates crypto : ECDSA for TLS

Cool stuff available esp-idf (esp32)

- IPv6 support
- 'Thread' IPv6-based IoT mesh-networking
- ESP-Adf audio framework (i2s, bluetooth, mp3, etc)
- ESP-CSI Use wifi as 'sensor'
- ESP-DSP Digital Signal Processing
- ESP-Wifi-Mesh Mesh-networking
- ESP-WHO Face Detecting with camera (!)
- 'EasyConnect' for WiFi (qr-code data)

ESP, typical application

- Connect to wifi or set up AP with webportal
- Read some sensors
- Drive some outputs
- Listen to commands from network
- Send status to network

ESP, typical application

- [khoih-prog/ESP_WiFiManager](#)
- Tons-of-libraries for input
- Tons-of-libraries for output
- [me-no-dev/ESPAsyncWebServer](#)
- [knolleary/pubsubclient](#)
- [bblanchon/ArduinoJson](#)

ESP typical application, caveats

- Define some kind of structured API
- Much of code is 'boilerplate', sometimes only small changes between projects
- Extending requires rewrites of API handling
- Interaction with 'other stuff' requires custom 'glue'

Alternative to building your own

- Existing projects
 - Tasmota
 - Espeasy
 - Espurna
- PRO's: flash once, config on device

Alternative to building your own

- Cons:
 - No 'code' to version/backup
 - Multiple versions for different uC's
 - Not much space left on device
 - Often not very 'structured' internally

ESPhome.io

- Based on PlatformIO (cli) framework.
- Designed for HomeAssistant, but useful without
- “Code” is a .yaml file
- Project-creation ‘wizard’
- ‘flashing’ via usb or OTA only what you **need**
- Structured API and ‘webserver’ module
- Esphome ‘dashboard’ for easy maintenance

ESPHome.io

- Provides abstract 'components'
- A 'component' can act upon others
- Tons of components and component-types
- Allows integration of custom code
- Provides 'filters' for data-transformation
- Provides 'automation' for on-device control

ESPHome.io - Demo

- esphome wizard tutorial.yaml
- esphome run tutorial.yaml
- compile, upload, logs
- esphome dashboard localhost

ESPHome.io, i2c-expander → switch

Example configuration entry

- pcf8574:
 - - id: 'pcf8574_hub'
 - address: 0x21
 - pcf8575: false
 -
- # Individual outputs
- switch:
 - - platform: gpio
 - name: "PCF8574 Pin #0"
 - pin:
 - pcf8574: pcf8574_hub
 - # Use pin number 0
 - number: 0
 - # One of INPUT or OUTPUT
 - mode: OUTPUT
 - inverted: false

ESPHome.io IR-receiver → switch

- # Example configuration entry
- remote_receiver:
 - pin: GPIO32
 - dump: all
 -
- binary_sensor:
 - - platform: remote_receiver
 - name: "Panasonic Remote Input"
 - panasonic:
 - address: 0x4004
 - command: 0x100BCBD

ESPHome.io , HX711 digital scale

sensor:

- - platform: hx711
- name: "HX711 Value"
- dout_pin: D2
- clk_pin: D1
- gain: 128
- update_interval: 1s
- filters:
 - - calibrate_linear:
 - - 49000 -> 0.00
 - - 117500 -> 2.776
- unit_of_measurement: kg

ESPHome.io – Things to note

- logger:

 baud_rate: 0 #disable UART logging

api:

 reboot_timeout: 0 # disables failsafe bootloop

- Use '-', not '_' in names for device/yaml

ESP8266 , ESP32 Conclusions

- Versatile platform
- Cheap
- Some 'polished' boards are better than Arduino hardware (m5stack)
- Hits sweet spot between 8bit μ C and 'full blown' Single-board-computer